

	⁷ Introduction
 Data T variab For or t 	ype: A <i>data type</i> is a term which refers to the kinds of data that les may "hold" in a programming language. example, a variable of type boolean can assume either the value true he value false, but no other value.
 Data compt 	Structure: A data structure is an arrangement of data in a iter's memory (or sometimes on a disk).
 In stru an a 	other words, a data structure is meant to be an organization or icturing for a collection of data items. A sorted list of integers stored in array is an example of such a structuring.
 Algasi 	orithms manipulate the data in these structures in various ways, such nserting a new data item, searching for a particular item, or sorting the



• Linear Data Structures

items.

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- A data structure whose elements form a sequence, and every element in the structure has a unique **predecessor** and unique **successor**.
- Examples: Array, Stack, Queue, Linked List

Non-Linear Data Structures

 A data structure whose elements do not form a sequence, there is no unique predecessor or unique successor.

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Examples: Tree, Graph

Common Operations on Data Structures

- Traversal: accessing or visiting each data item exactly once
- Searching: finding the data item within the data structure which satisfies searching condition
- Insertion: adding a new data element within the data structure
- Deletion: removing a new data element from the data structure
- Sorting: arranging the data in some logical order
- Merging: combining the data elements of two data structures

Array
An array is a fixed-size sequential collection of elements of same data type.
An array is simply a grouping of like-type data.
In its simplest form, an array can be used to represent a list of numbers, or a list of names.
Some examples where the concept of an array can be used:
 List of temperatures recorded every hour in a day
 List of employees in an organization
 Test scores of a class of students
Table of daily rainfall data

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One-Dimensional Array • A list of items can be given one variable name using only one subscript and such a variable is called a single-scripted variable of a onedimensional array.

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- Declaration: data-type variable-name[size];
- Declaration Examples: float height[50];
 - int group[10];

char name[10];

One-Dimensional Array	
Initialization at Compile Time:	
<pre>data-type variable-name[size] = {list of values};</pre>	
Compile Time Initialization Examples	
<pre>int number[3] = {5, 6, 7};</pre>	
<pre>int age[5] = {22, 24, 23}; > Remaining two elements will be initialized to</pre>	0.
<pre>int counter[] = {1, 2, 3, 4, 5}; > The array size may be omitted.</pre>	
<pre>char city[5] = {'D', 'E', 'L'};</pre>	NULL.





Calculating Address of Elements in 1D Array

- Let x [n] be an one-dimensional array having n elements with indices
 i = 0, 1,, n-1.
- Then, the address of i^{th} element (x [i]) is calculated as follows:

Base Address + (i × Scale Factor of Data Type of Array)

Example: Given an array x[5] of integers with base address = 1000. Calculate the address of element x[3].

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Address of x[3] = Base Address + (3 × Scale Factor of Integer)

 $= 1000 + (3 \times 2) = 1006$

Two-Dimensional Array • Declaration: data-type variable-name[row-size] [column-size]; • Declaration Examples: float sales[3][3]; int matrix[4][3];



	Representation of 2D Arra						
	Column0	Column1	Column2				
Row 0>	310	275	365				
	[1][0]	[1][1]	[1][2]				
Row 1>	10	190	325				
	[2][0]	[2][1]	[2][2]				
Row 2 >	405	235	240				
	[3][0]	[3][1]	[3][2]				
Row 3>	310	275	365				

Memory Layout of 2D Array
• There are two main techniques of storing 2D array elements into memory:
 Row Major Ordering
\circ All the <code>rows</code> of the 2D array are stored into the memory contiguously.
Column Major Ordering
\circ All the columns of the 2D array are stored into the memory contiguously.

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Calculating Address of Elements in 2D Array

- Let x [m] [n] be a two-dimensional array having m rows and n columns with indices i = 0, 1,, m; j = 0, 1,n.
- Then, the address of an element x[i][j] of the array, stored in Row Major, is calculated as:

Base Address + (i × n + j) × Scale Factor of Data Type of Array

Example: Given an array x[5][7] of integers with base address = 900. Calculate the address of element x[4][6].

Address of x[4][6] = 900 + (4 × 7 + 6) × 2 = 968

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Question: Given an array [1...5, 1...7] of integers with base address = 900. Calculate address of element [4, 4].

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нал	Calculating Address of Elements in 2D Arra	y
•	Let $x [m] [n]$ be a two-dimensional array having m rows and n column with indices i = 0, 1,, m; j = 0, 1,n.	s
•	Then, the address of an element $\texttt{x[i][j]}$ of the array, stored in Column Major, is calculated as:	n
	Base Address + (j \times m + i) \times Scale Factor of Data Type of Array	
	Example: Given an array x[5][7] of integers with base address = 900. Calculate the address of element x[4][6].	
	Address of x[4][5] = 900 + (5 × 5 + 4) × 2 = 958	

Question: Given an array [1...5, 1...6] of integers with base address = 2000. Calculate address of element [4, 4].

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Lanan water	Sparse Matrix						
 A matrix can be defined as a two-dimensional array having 'm' columns and 'n' rows representing m×n matrix. 							
 Sparse matrices are elements equal to ze In other words, the 	 Sparse matrices are those matrices that have the majority of their elements equal to zero. In other words, the coarse matrix is a matrix that has a greater number of zero. 						
elements than the no	lements than the non-zero elements.						
	0 1 2 3						
0	0	4	0	5			
1	0	0	3	6			
4	ō	ŏ	ŏ	ŏ			
					1		
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Storage

 We need to store m×n (all elements) elements of matric even though maximum number of elements of the matrix are zero.

• Computing Time

 In case of searching (or performing any operation) in a sparse matrix, we need to traverse m×n (all elements) rather than accessing non-zero elements of the sparse matrix.

Sparse Matrix Representation

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- The non-zero elements can be stored with triples, i.e., rows, columns, and value.
- The sparse matrix can be represented in the following ways:
 - Array Representation
 - Linked List Representation
 - List of Lists Representation

Sparse Matrix: Triples/Array Representation)

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 A 2D array with 3 row or columns is used to represent the sparse matrix:

- Row: It is an index of a row where a non-zero element is located.
- Column: It is an index of the column where a non-zero element is located.
- Value: The value of the non-zero element is located at the index (row, column).





Sparse Matrix: Linked List Representation

• A linear linked list is used to represent the sparse matrix. Each node of the list consists of four fields:

- Row: Row: An index of row where a non-zero element is located.
- Column: An index of column where a non-zero element is located.
- Value: Value of the non-zero element which is located at the index (row, column).





Sparse Matrix: List of List Representation
 One list is used to represent the rows, and each row contains the list of triples:
Column: An index of column where a non-zero element is located.
• Value: Value of the non-zero element.
Address of Next Node : It stores the address of the next non-zero element.



Linear Search

- Searching is a process of finding a value in a list of values.
- Linear search is a very simple search algorithm.

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- In this type of search, a sequential search is made over all items one by one.
- Every item is checked and if a match is found then that particular item is returned, otherwise the search continues till the end of the data collection.
- It has a time complexity of O(n), which means the time is linearly dependent on the number of elements, which is not bad, but not that good too.

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Linear Search: Step-by-Step Process

- Step 1: Read the element to be searched from the user
- Step 2: Compare, the element to be searched with the first element in the list.
- Step 3: If both are matched, then display "Given element found" and terminate the search process.
- Step 4: If both are not matched, then compare search element with the next element in the list.
- Step 5: Repeat steps 3 and 4 until the search element is compared with the last element in the list.
- Step 6: If the last element in the list is also not matched, then display "Element not found!" and terminate the function.

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Binary Search: Step-by-Step Process

- Step 1: Read the element to be searched from the user.
- Step 2: Find the middle element in the sorted list.

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- Step 3: Compare, the search element with the middle element in the sorted list.
- Step 4: If both are matched, then display "Given element found!" and terminate the search
 process.
- Step 5: If both are not matched, then check whether the search element is smaller or larger than middle element.
- Step 6: If the search element is smaller than middle element, then repeat steps 2, 3, 4 and 5 for the left sub-list of the middle element.
- Step 7: If the search element is larger than middle element, then repeat steps 2, 3, 4 and 5 for the right sub-list of the middle element.
- Step 8: Repeat the same process until we find the search element in the list or until the sub-list contains only one element.
- Step 9: If that element also doesn't match with the search element, then display "Element not found in the list!" and terminate the function.

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BHANT	Program Code for Binary Sea	rch
low=0;		
high=n-1;		
while(low<=	high) {	
mid=	(low+high)/2;	
if(i	tem <a[mid])< th=""><th></th></a[mid])<>	
	high=mid-1;	
else	<pre>if(item>a[mid])</pre>	
	low=mid+1;	
else	<pre>if(item==a[mid]) {</pre>	
	<pre>printf("Item Found");</pre>	
	break;	
}		
else	{	
	<pre>printf("Not Found");</pre>	
}		
}		
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Selection Sort: Step-by-Step Process

- Step 1: Select the first element of the list (i.e., element at first position in the list).
- Step 2: Compare the selected element with all other elements in the list.
- Step 3: For every comparison, if any element is smaller than selected element (for ascending order), then these two are swapped.
- Step 4: Repeat the same procedure with next position in the list till the entire list is sorted.

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• Complexity: O(n²)

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Bubble Sort: Step-by-Step Process

- Step 1: Select the first element of the list (i.e., element at first position in the list).
- Step 2: Compare the current element with next element of the list.
- Step 3: If the current element is greater than the next element (for ascending order), then these two are swapped.
- Step 4: If the current element is less than the next element, move to the next element.
- Step 5: Repeat from Step 1.
- Complexity: O(n²)

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Consider the following unsorted list of elem 14 33 27 35 10 Iteration 1:	nents: After Iteration 2
14 33 27 35 10 Iteration 1:	After Iteration 2
Iteration 1:	After Iteration 2
14 33 27 35 10	14 27 10 33 35
14 33 27 35 10	After Iteration 3
14 27 33 35 10 ← 14 33 27 35 10	14 10 27 33 35
14 27 33 35 10	After Iteration 3
14 27 33 35 10	
14 27 33 10 35 ← 14 27 33 35 10	





Insertion Sort: Step-by-Step Process

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- Step 1: Assume that first element in the list is in sorted portion of the list and remaining all elements are in unsorted portion.
- Step 2: Consider first element from the unsorted list and insert that element into the sorted list in order specified.
- Step 3: Repeat the above process until all the elements from the unsorted list are moved into the sorted list.
- Complexity: O(n²)

Insertion Sort: Working Example									
Consider the following unsorted list of elements:									
	15	20	10	30	50	18	5	45	
Assume that the sorted portion of the list is empty and all elements in list are in unsorted portion, as shown below: Sorted Unsorted									
	15	20	10	30	50	18	5	45	
Move the first element 15 from the unsorted portion to sorted portion.									
Sorted Unsorted									
		20	10	30	50	18	5	45	















for(i=1; i <n; i++)<="" th=""></n;>
{	
	<pre>temp = data[i];</pre>
	j = i-1;
	<pre>while(temp<data[j] &&="" j="">=0)</data[j]></pre>
	{
	<pre>data[j+1] = data[j];</pre>
	j = j-1;
	}
	<pre>data[j+1]=temp;</pre>
}	

Shell Sort
n Insertion Sort, a large number of swaps/shifts are performed to sort he elements.
hell sort is an efficient sorting algorithm and is based on Insertion Sort.
his algorithm avoids large shifts as in case of Insertion Sort, if the maller value is to the far right and has to be moved to the far left.
hell Sort compares items that lie far apart which allows elements to nove faster to the front of the list.

BHANT COME	Shell Sort: Algorithm Working	
1.	Divide the list into sub-lists using interval Floor(N/2^k) .	
2.	Shell Sequence (Floor(N/2*)) Short sub-lists using Insertion Sort.	
3.	Repeat until complete list is sorted.	
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Radix Sort

• A list of numbers is sorted based on the digits of individual numbers.

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- Sorting is performed from least significant digit to the most significant digit.
- The number of passes required are equal to the number of digits present in the largest number of the list.
 - Example: If the largest number has 3 digits, then the list will be sorted in 3 passes.

Radix Sort: Algorithm

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- 1. Define 10 queues, each representing a bucket for each digit from 0 to 9.
- Consider the least significant digit of each number in the list which is to be sorted.
- 3. Insert each number into their respective queue based on the least significant digit.
- Group all the numbers from queue 0 to queue 9 in the order they have inserted into their respective queues.
- Repeat from step 2 until all the numbers are grouped based on the most significant digit.

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Quick Sort: Procedure/Process

- The quick sort uses <u>divide and conquer</u> to gain the same advantages as the merge sort, while not using additional storage.
- A quick sort first selects a value, which is called the pivot value. The
 <u>actual position</u> where the pivot value belongs in the final sorted list,
 commonly called the <u>split point</u>, is used to divide the list for subsequent
 calls to the quick sort.
- Partitioning begins by locating two position markers—let's call them leftmark and rightmark — <u>at the beginning</u> and <u>end of the remaining</u> <u>items in the list</u>.

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Quick Sort: Procedure/Process

- Begin by incrementing leftmark until we locate a value that is greater than the pivot value.
- Then decrement rightmark until we find a value that is less than the pivot value.
- At the point where rightmark becomes less than leftmark, we stop.
 - The position of rightmark is now the split point.
 - The pivot value can be exchanged with the contents of the split point and the pivot value is now in place.

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Linked List

- Linked List is a linear collection of data elements, called *nodes*.
- The linear order is given by pointers.
- Each node is divided into two or more parts.
- A Linked List can be of following types:
 - Linear Linked List (One-Way List)
 - Doubly Linked List (Two-Way List)
 - Circular Linked List

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NODE *noc	;		
node=(NOE	*)malloc(sizeof(NODE)));	
if(start=	=ILEM, NULL) {		
node->r	ext=NULL;		
}			
else {			
node->r	ext=start;		
start=noc	·:		
	- ,		

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//0	Deletion of a Node from the <u>Beginning</u> of a Linear Linked List
voi	id deleteBegin() {
	NODE *node;
	if(start==NULL) {
	<pre>printf("\nUNDERFLOW");</pre>
	return;
	}
	else {
	node=start;
	<pre>start=start->next;</pre>
	<pre>printf("NODE DELETED %d ", node->data);</pre>
	<pre>free(node);</pre>
	}
3	







	Traversal of a Linear Linked Lis	st
//Traversal of a Li	inear Linked List	
<pre>void travers() {</pre>		
NODE *pos;		
pos=start;		
if(pos==NULL) {		
printf("\nl	IST IS EMPTY");	
}		
else {		
printf("\nl	IST ELEMENTS: ");	
while(pos!=	NULL) {	
printf(("%d ",pos->data);	
pos=pos-	>next;	
}		
}		
}		
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Stack

- A Stack is a linear data structure.
- It is a list in which insertion of new data item and deletion of existing data item is done from one end, known as **Top** of Stack.
- Stack is also called LIFO (Last-in-First-out) type of list.
 - The last inserted element will be the first to be deleted from Stack.
- Example:

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 Some of you may eat biscuits (or poppins). If you assume only one side of the cover is torn and biscuits are taken out one by one. This is called poping. If you want to preserve some biscuits for some time later, you will put them back into the pack through the same torn end. This is called pushing.

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Operations on Stack

• Push

- The process of inserting a new element to the top of stack is called Push operation.
- In case the list is full, no new element can be accommodated, it is called Stack Overflow condition.

• Pop

- The process of deleting an element from top of stack is called Pop operation.
- If there is no any element in the Stack and Pop is performed then this will result in Stack Underflow condition.

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Implementation of Stack Static Implementation It is achieved using Array Dynamic Implementation It is achieved using Linked List

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Operation
<pre>stack[10],top = -1; push(int x) top = top+1; stack[top] = x;</pre>
Operation pop() int temp; temp = stark[ton]:

Implementation of Stack using Link	ed Lis
Structure Definition	
<pre>struct stack { int data; struct node *next; }; turedef struct stack STACK:</pre>	
STACK *top;	
STACK +top: Required Functions	
STACK +top; Required Functions void create();	
STACK *top; Required Functions void create(); int isempty();	
<pre>STACK *top; Required Functions void create(); int isempty(); int isfull()</pre>	
STACK +top: Required Functions void create(); int issempt(); int isfull() void point(int);	
<pre>STACK +top; Required Functions void create(); int isempty(); int isfull() void push(int); int pop();</pre>	

uaat	Some Applications of Stack
•	Reverse of String/Number
•	Recursion (Recursive Function)
•	Expression Conversion
•	Expression Evaluation
•	Syntax Parsing
•	Undo-mechanism in an Editor
•	etc.

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Expressions and their Types

- An expression is defined as a number of operands or data items combined using several operators.
- The way to write arithmetic expression is known as a notation.
- An arithmetic expression can be written in three different but equivalent notations, i.e., without changing the essence or output of an expression.
- These notations are:
 - Infix Notation
 - Prefix Notation
 - Postfix Notation

Infix Notation

- Infix Notation is what we come across in our general mathematics.
- In Infix Notation, operators are written *in-between* the operands.
- Example:

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• Expression to add two numbers A and B is written as:

A + B

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• Infix Notation needs precedence of the operators and we sometimes use bracket () to override these rules.

Prefix Notation

- In Prefix Notation, operators are written *before* the operands.
- This is also known as *polish notation* in the honor of the Polar mathematician (Jan Lukasiewicz) who developed this notation.
- Example:

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• Expression to add two numbers A and B is written as:

+ A B

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Postfix Notation

- In **Postfix Notation**, operators are written *after* the operands.
- This is also known as *reverse polish notation*.
- Example:

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• Expression to add two numbers A and B is written as:

A B +

- It is most suitable for computer to calculate any expression as there is no need for operator precedence and other rules.
- It is the universally accepted notation for designing ALU of the CPU, therefore important for us to study.

<i>۱</i> ر هو	Conversion from Infix to Postfix Notation
٠	While there are tokens to be read from expression, read the token.
•	If the token is an operand, then insert it to output.
•	If the token is an operator and if the Top of Stack is not any operator then push the operator to stack.
•	If the token is an operator O1:
	 While there is an operator, O2 at top of stack (O2 is Top), and
	 If precedence of O1 > O2
	✓ Push O1 on to Stack (now O1 is Top)
	 Else if precedence of O1 <= O2
	✓ Pop O2 to the output and Push O1 onto Stack
•	If the token is a left parenthesis, the Push it onto the Stack.
•	If the token is a right parenthesis:

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- - Until the token at Top is a left parenthesis, Pop operators off the Stack onto the output

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- Pop the left parenthesis from Stack
- If the token at Top is an operator, Pop and insert it onto output.

Step-by-S	tep Example: Infix to Postfix Convers	sion
	Infix (a+b-c)*d-(e+f) Postfix	



Step-by-St	tep Example: Infix to Postfix Conver	sion
Stack	Infix a + b - c) * d – (e + f) Postfix	
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Step-by-Step Example: Inf	x to Postfix Conversion
Stack Infix + b - c)* Postfix a	d – (e + f)
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вилат	tep Example: Infix to Postfix Conve	rsion
Stack	Infix - c) * d – (e + f) Postfix a b	
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зыкал	ep Example: Infix to Postfix Conver	sion
	Infix * d – (e + f) Postfix a b + c -	
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Step-by-Step Example: Infix to Postfix Conversion	h
Stack Infix (e+f) Postfix a b + c - d * Infix	
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Step-by-Step Example: Infix to Postfix Conversion
Stack Infix f) Postfix + a b + c - d * e
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Step-by-St	ep Example: Infix to Postfix Conv	ersion
Stack	Infix Postfix a b + c - d * e f +	
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Step-by-Step Example: Infix to Postfix Conversion	
Stack Infix Postfix a b + c - d * e f + -	
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Inf	ix to Pos	tfix Co	nversion: Ex	ample
Conv	ert ((A – (B + C)) * D) ^(E +	F) to Postfix form.	
SYMBOL	POSTFIX STRING	STACK	REMARKS	
((
(((
A	A	((
	A	((-		
(A	((-(
В	AB	((-(
+	A B	((-(+		
С	ABC	((-(+		
)	ABC+	((-		
)	A B C + -	(
•	A B C + -	(*		
D	A B C + - D	(*		
)	A B C + - D *			
↑	A B C + - D *	î		
(A B C + - D *	î (
E	A B C + - D * E	↑ (
+	A B C + - D * E	↑(+		
F	A B C + - D * E F	î(+		
)	A B C + - D * E F +	1		
End of string	A B C + - D * E F + ↑	The input is now from the stack un	empty. Pop the output symbols til it is empty.	

Conversion from Infix to Prefix Notation

- The conversion process is almost same according to Postfix notation.
 - The only change from Postfix form is that traverse the expression from right to left and the operator is placed before the operand rather than after them.

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- Convert the expression A * B + C / D into Prefix notation.
 - Answer: + * A B/ C D

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Conversion from Postfix to Infix Notation

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1. Scan the postfix expression from left to right.

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- 2. If the scanned symbol is an operand, then push it onto the stack.
- 3. If the scanned symbol is an operator, pop two symbols from the stack and create it as a string by placing the operator in between the operands and push it onto the stack.
- 4. Repeat steps 2 and 3 till the end of the expression.

BILAND DIFFERENCE POSTFIX to	o In	fix Conversion	on: Example
	Symbol	Stack	Remarks
Convert the expression A	A	A	Push A
		AB	Push B
BC*DEF*/G*-H+*	с	A B C	Push C
to Infix notation.		A (B*C)	Pop two operands and place the operator in between the operands and push the string.
	D	A (B*C) D	Push D
	ε	A (B*C) D E	Push E
	F	A (B*C) D E F	Push F
	^	A (B*C) D (E^F)	Pop two operands and place the operator in between the operands and push the string.
	/	A (B*C) (D/(E^F))	operator in between the operands and push the string.
	G	A (B*C) (D/(E^F)) G	Push G
	•	A (8*C) ((D/(E^F))*G)	Pop two operands and place the operator in between the operands and push the string.
		A ((B*C) = ((D/(E^F))*G))	operator in between the operands and push the string.
	н	A ((B*C) = ((D/(E^F))*G)) H	Push H
	•	A (((B*C) - ((D/(E^F))*G)) * H)	Pop two operands and place the operator in between the operands and push the string.
	+	(A + (((B*C) - ((D/(E^F))*G)) * H))	
	End of string	The input is now empty. The string formed	is infix.
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Infix to Postfix Conversion: Questions
• A * B + C
• A + B * C
• A * (B + C)
• A – B + C
• A * B ^ C + D
• A * (B + C * D) + E
• $(A + B) * C / D + E ^ F / G \rightarrow A B + C * D / E F ^ G / + (Answer)$
 A + (B * C − (D / E ^ F) * G) * H → A B C * D E F ^ / G * - H * + (Answer)
 A - B / (C * D ^ E) → A B C D E ^ * / - (Answer)

Step	Input	Operation	Stack	Calculation
1	4	Push	4	
2	5	Push	4 5	
3	6	Push	456	
4	*	Pop 2 Elements and Evaluate	4	6 * 5 = 30
5		Push Result (30)	4 30	
6	+	Pop 2 Elements and Evaluate	Empty	4 + 30 = 34
7		Push Result (34)	34	
8		No More Elements (Pop)	Empty	34

Double Stack/Multistack

- Double stack means two stacks which are implemented using a single array.
- To prevent memory wastage, the two stacks are grown in opposite direction.
- The pointer Top1 and Top2 points to top-most element of Stack1 and Stack 2 respectively.
- Initially, Top1 is initialized to -1 and Top2 is initialized the size of array.
- As the elements are pushed into Stack1, Top1 is incremented.
- Similarly, as the elements are pushed into Stack2, Top2 is decremented.
- The array is full when Top1=Top2-1.
- Multistack means more than 2 stacks which are implemented using a single array. puter Applications and Management, New Delhi-63, by Dr. Sunil Pratap

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Queue

- A Queue is a linear data structure.
- It is a list in which insertion of new data items is done from one end, called Rear end, and deletion of existing data item is done from other end, known as Front end of Queue.
- Queue is also called FIFO (First-in-First-out) type of list.
 - The first inserted element will be the first to be deleted from Queue.

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Working of Queue • Enqueue • The process of inserting a new element at the Back of queue is called Enqueue operation. In case the list is full, no new element can be accommodated, it is called Queue Overflow condition.

Dequeue

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- The process of deleting an element from Front of queue is called Dequeue operation.
- If there is no any element in the queue and Dequeue is performed then this will result in Queue Underflow condition.

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Memory Implementation of Queue using Linl	ked Lis
Structure Definition	
<pre>struct queue { int data; struct node *next; };</pre>	
typedet struct queue QUEUE; QUEUE *start;	
Typeder struct queue QUEUE; QUEUE *start; Required Functions	
typedet struct queue QUEUE; QUEUE *start; Required Functions void create();	
<pre>typedet struct queue QUEUE; QUEUE *start; Required Functions void create(); int isempty();</pre>	
<pre>typeder struct queue QUEUE; QUEUE *start; Required Functions void create(); int ismpty(); int isfull()</pre>	
<pre>typeder struct queue Queue; QUEUE *start; Required Functions void create(); int isempty(); int isfull() void enqueue(int);</pre>	
<pre>typeder struct queue QUEUE; QUEUE *start; Required Functions void create(); int isempty(); int isfull() void enqueue(int); int dequeue();</pre>	

Implementation of Queue using Linked List

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- In Queue, insertion takes place at Rear end.
 - This is similar to inserting an element at the <u>end</u> of a Linked List.
- In Queue, deletion takes place at Front end.
 - This is similar to deleting an element from the <u>front</u> of a Linked List.
- Therefore, Linked List has application in implementing a Queue.





Structure for a Queue using Linker	d List
struct queue	
{	
struct node *next:	
<pre>};</pre>	
typedef struct queue QUEUE;	
QUEUE *start;	
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int	dequeue()	
{		
	QUEUE *node;	
	int item;	
	if(start != NULL)	
	{	
	node = start;	
	<pre>item = node->data;</pre>	
	<pre>start = start->next;</pre>	
	<pre>free(node);</pre>	
	<pre>return (item);</pre>	
	}	
	else	
	return 0;	
}		

Multiqueue

Maintaining two or more queues in the same array refers to Multiqueue.

Front

Rear0

4 5 6 7 8 9

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• Double Queue:

0 1

2 3

Rear(









Circular Queue

• Circular Queue is a linear data structure

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- The operations are performed based on FIFO (First In, First Out)
 principle
- The last position is connected back to the first position to make a circle

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<pre>//Method 1 to Check Queue Overflow int isFull() { if((front == rear + 1) (front == 0 && rear == SIZE-1)) return 1; else return 0; } //Method 2 to Check Queue Overflow int isFull() { if((rear+1) % SIZE == front) return 1; else return 0; } int isEmpty() { if(front == -1) return 1; else } return 0; } </pre>	Implementing Circular Queue using	Array
<pre>//Method 2 to Check Queue Overflow int isFull() { if((rear+1) % SIZE == front) return 1; else return 0; } int isEmpty() { if(front == -1) return 1; else return 0; }</pre>	<pre>//Method 1 to Check Queue Overflow int isFull() { if((front == rear + 1) (front == 0 && rear == SIZE-1)) return 1; else return 0; }</pre>	
<pre>int isEmpty() { if(front == -1) return 1; else return 0;</pre>	<pre>//Method 2 to Check Queue Overflow int isFull() { if((rear+1) % SIZE == front) return 1; else return 0; }</pre>	
3	<pre>int isEmpty() { if(front == -1) return 1; else return 0; }</pre>	





Deletion in Circular Queue using A	rray
<pre>int delete() {</pre>	
int item;	
<pre>if(isEmpty()) {</pre>	
<pre>printf("UNDERFLOW!");</pre>	
return(-1);	
}	
else {	
<pre>item = queue[front];</pre>	
if(front == rear) {	
<pre>front = -1;</pre>	
rear = -1;	
}	
else {	
<pre>front = (front + 1) % SIZE;</pre>	
}	
<pre>printf("ITEM DELETD %d", item);</pre>	
return (element);	
}	
}	
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1nt · {	travers()	
· .	int i;	
	if(isEmpty())	
	<pre>printf("UNDERFLOW!");</pre>	
	else	
	{	
	<pre>printf("ITEMS: ");</pre>	
	<pre>for(i = front; i!=rear; i=(i+1)%SIZE) {</pre>	
	<pre>printf("%d ",queue[i]);</pre>	
	}	
	<pre>printf("%d ",queue[i]);</pre>	
	}	
}		

Deque (Double Ended Queues)

- Insertion and Deletion are performed from both the ends, i.e.,
 - we can insert/delete elements from the REAR end or from the FRONT end
- Four operations are performed:

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- Insertion of an element at the REAR end of Queue.
- Deletion of an element from the FRONT end of Queue.
- Insertion of an element at the FRONT end of Queue.
- Deletion of an element from the REAR end of Queue.
- There are two types of Deques:
 - Input-restricted Deque: Deletion can be performed from both ends (FRONT and REAR) while Insertion can be done at one end (REAR)
 - Output-restricted Deque: Deletion can be performed from one end (FRONT) while Insertion can be done at both ends (REAR and FRONT)

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Methods to be implemented for Deque int isEmpty() int isFull()

void insertFront(int x)

void insertRear(int x)

int deleteFront()

int deleteRear()

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